

Element failure probability of soil slope under consideration of random groundwater level

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Abstract: The instability of soil slopes is directly related to both the shear parameters of the soil material and the groundwater, which usually causes some uncertainty. In this study, a novel method, the element failure probability method (EFP), is proposed to analyse the failure of soil slopes. Based on the upper bound theory, finite element discretization, and the stochastic programming theory, an upper bound stochastic programming model is established by simultaneously considering the randomness of shear parameters and groundwater level to analyse the reliability of slopes. The model is then solved by using the Monte-Carlo method based on the random shear parameters and groundwater levels. Finally, a formula is derived for the element failure probability (EFP) based on the safety factors and velocity fields of the upper bound method. The probability of a slope failure can be calculated by using the safety factor, and the distribution of failure regions in space can be determined by using the location information of the element. The proposed method is validated by using a classic example. This study has theoretical value for further research attempting to advance the application of plastic limit analysis to analyse slope reliability.

Keywords: soil slope; reliability; element failure probability; upper bound method; finite element discretization; stochastic programming

30 **Introduction**

31 Computation of the soil slopes stability is complex and uncertain as many factors may affect the
32 stability of soil slopes. Among these factors, the soil shear parameters and groundwater are the most
33 important ones and have significant effects on the reliability of soil slopes (Dai et al. 2002). Shear
34 parameters are natural characteristics of the soil material of the slope and are directly related to the
35 mechanical properties of the soil mass, such as the resistance to a landslide in the inner slope. The
36 composition and random distribution of the soil material determines the variation and uncertain
37 characteristics of the shear parameters of the soil mass. Variation in groundwater level often results
38 in a landslide of the soil slope (Ching et al.2016; Cafaro and Cherubini 2002; Chen and Mayne 1996;
39 Cho 2007). This effect is observed because the presence of groundwater can strongly reduce the
40 shear resistance of soil, and variation of the seepage fields of a slope further changes the pore water
41 pressure in soil (Ali and Lyamin 2014; Chiu et al. 2012; Lu and Griffiths 2004; Wang et al. 2019).
42 Since both the soil shear parameters and the groundwater distribution in a slope have random
43 characteristics, a random influence caused by these two factors should be considered in the stability
44 analysis of the soil slope.

45 Extensive studies based on the rigid body limit equilibrium and the finite element methods have
46 been conducted to investigate the slope reliability. The rigid limit equilibrium-based analysis could
47 directly yield a mathematical distribution and the failure probability of the safety factor. This
48 method is effective and widely employed, but the slip surface of a slope needs to be artificially
49 determined (Malkawi and Hassan 2000; Ji et al. 2020; Lu and Griffiths 2004; Low et al. 2007).
50 Finite element method (FEM) analysis is theoretically stricter than the former method. The
51 stress-strain distribution in the inner of slope could be obtained by using FEM, but it is
52 computationally costly (Griffiths and Fenton 2004; Griffiths et al. 2009; Dyson and Tolooiyan
53 2020). Recently, slope reliability analysis based on the plastic limit theory has been significantly
54 developed. By using this method, a limit condition of the slope under instability could be obtained
55 without considering the loading history of the slope or the constitutive relation of the soil material.
56 The ultimate load (or safety factor) and the failure mechanism (stress field and velocity field) of the
57 slope could also be obtained (Huang et al. 2013; Li and Liu. 2001; Zhang et al.2018; Li et al. 2019;
58 Ali et al. 2017; Kasama and Whittle. 2011; Zhao et al. 2016). Since the analysis is greatly simplified,
59 the plastic limit-based method has great potential applications in slope reliability analysis.

60 The integrated failure probability method is conventionally used to analyse slope failure, in which
61 the overall failure of a slope is determined by a safety factor threshold of 1.0. The failure probability
62 of the slope is calculated thereafter (Phoon and Kulhawy. 1999; Huang et al.2010). However,
63 different failure modes of the soil slope would result in different failure consequences (sliding
64 volume). For example, there is large difference in the failure consequence between deep sliding and

65 near-surface sliding; however, the conventional method does not consider such differences and only
66 considers whether the safety factor is less than 1.0. As a result, the distribution difference of the
67 failure regions in the space of a slope is overlooked (Jiang et al. 2014; Low et al.2011; Li et al. 2019).
68 To date, there have been great achievements on the relationship between the random parameters and
69 failure modes of slope. However, the relationship between spatial distribution of failure probability
70 and groundwater level has not been studied systematically. Novel theory and methods are required
71 to solve this issue.

72 In this study, we apply the random distribution model of the shear parameters and the groundwater
73 level of soil slopes together with their sampling. Based on the upper bound theory, the finite element
74 discretization technique, the stochastic programming theory, and the Monte-Carlo method, an upper
75 limit numerical method is developed to analyse the reliability of soil slopes by considering the shear
76 parameters and the random groundwater level. A method is proposed to analyse the element failure
77 probability (**EFP**) of soil slopes. This analysis provides novel theory and method for the failure
78 analysis of soil slopes and the relationship between the groundwater levels of soil slopes and the
79 failure probability. Additionally, this study investigates the evolution of the failure probability of
80 soil slopes.

81 **Random seepage field of soil slope**

82 The soil body is a typical three-phase medium. The pore water flow in the soil mass forms seepage
83 field. The existence condition of the soil slope is highly complicated. The seepage field in the soil
84 slope is influenced by many random parameters with two important parameters. The first important
85 parameter is the random distribution of the soil particles and pores in the soil mass, which results in
86 random permeability of the soil material. The second important parameter is the random supply (i.e.,
87 rain, ground run-off, and irrigation) and drain (i.e., evaporation, ground pumping, and soil
88 excavation) of the groundwater in the soil slope, which results in uncertain groundwater level in the
89 soil slope. Consequently, the seepage flow in the soil slope has a random characteristic.

90 Extensive studies have been performed to investigate the influence of the random permeability of
91 the soil material on the seepage field of the soil slope. These studies include the investigation of the
92 effect of permeability variation on the stable seepage field, the random permeability-based analysis
93 of slope seepage, and the random probability analysis of slope instability caused by permeation
94 (Yang et al. 2004; Cho. 2012; Mouyeaux et al. 2019; Griffiths and Fenton.1998). However, few
95 studies have been conducted to investigate the influence of the random groundwater on the random
96 seepage field and reliability of soil slopes, which motivates this study. To this end, a plastic limit
97 analysis numerical model of soil slopes is developed by considering the shear parameters and the
98 random groundwater levels.

99 The seepage problem of the soil slope under the action of the random groundwater levels is shown
100 in Figure 1. To simplify the analysis, this paper makes the following assumptions: (1) assuming that
101 the soil slope groundwater level H_w^r is a random variable and varies randomly between the lower
102 and upper bounds. Assuming that the underground water level at the slope angle is determined, the
103 soil permeability coefficient is considered a determined parameter during the calculation of the
104 random seepage field. (2) Only the saturated and stable seepage field of soil slope under the action
105 of the random groundwater level is calculated, and the excess pore water pressure caused by sudden
106 increase or decrease in water level is not considered. (3) The random variation of the groundwater
107 level H_w^r will result in a random change of the saturation line location, assuming that the soil pore
108 water pressure p^r at an arbitrary point K' above the saturation line is zero and is a random
109 variable below the saturation line (as shown in Figure 1). The pore water pressure p^r and has a
110 direct correlation with H_w^r .

111 **Function of the reliability analysis of soil slopes**

112 In calculating the stability of soil slopes, there are two general methods to make the slope reach the
113 limit state of the instability. The first method is to find the overload coefficient by gradually
114 increasing the external load, while the second approach is to find the safety factor by gradually
115 reducing the shear parameters of the soil material. Because the instability of the soil slope is related
116 to many random parameters, the overload coefficient and the safety factor are random variables.
117 In this study, the volume weight overload is used to make the soil slope reach the limit state of the
118 instability. The random quantity of the volume weight overload factor is defined as

$$119 \quad \lambda_\gamma^r = \frac{\gamma_c(c^r, \phi^r, H_w^r)}{\gamma_a} \quad (1)$$

120 where λ_γ^r is the random variable of the overload factor of volume weight and relates to c^r , ϕ^r ,
121 and H_w^r ; $\gamma_c(c^r, \phi^r, H_w^r)$ is the random variable of the ultimate value of volume weight when the
122 soil reaches the limit state; c^r and ϕ^r are random variables of the cohesion and the internal
123 friction angle of the soil materials; and γ_a is the real volume weight of the soil material.

124 The random quantity of the soil slope safety factor is defined as:

$$125 \quad \lambda_m^r = \frac{c^r}{c'^r} = \frac{\phi^r}{\phi'^r} \quad (2)$$

126 where λ_m^r is the random variable of the safety factor that relates to c^r , ϕ^r , and H_w^r ; c^r and c'^r
127 are the random quantity of cohesion before and after the intensity reduction, respectively; ϕ^r and
128 ϕ'^r are the random quantity of the internal friction angle before and after the intensity reduction,

129 respectively.

130 In this study, the limit state equation for the reliability analysis of the soil slope is developed by
131 considering the shear parameters of the soil material and the randomness of the ground water level.

132 The limit state function of the soil slope reliability is defined as:

$$133 \quad Z = (\lambda_m^r - 1.0) \begin{cases} > 0, & \text{Stable} \\ = 0, & \text{Critical state} \\ < 0, & \text{Failure} \end{cases} \quad (3)$$

134 Equation (3) shows that when $Z > 0$, that is, the safety factor $\lambda_m^r > 1.0$, the slope is in a stable state.

135 When $Z = 0$, that is, the safety factor $\lambda_m^r = 1.0$, the slope is in a critical state. When $Z < 0$, that is, the
136 safety factor $\lambda_m^r < 1.0$, the slope is in a failure state.

137 **Stochastic programming model of upper bound method**

138 The upper bound theorem of plastic limit analysis is an efficient tool for solving the stability of soil
139 slope. According to the upper bound theorem, among all the external loads corresponding to the
140 kinematically admissible velocity fields, the minimum external load is the closest to the real load.

141 This property means that the upper bound method is a mathematical programming problem for
142 finding the minimum value of an external load. Extensive studies have been conducted by using the
143 upper bound numerical method of plastic limit analysis to perform the deterministic analysis of soil
144 slopes (Zhang et al. 2018; Sloan and Kleeman. 1995; Kim and Salgado. 1999, (Li et al. 2018)).

145 Based on the previous work of Sloan and Kim, this study establishes an upper bound method
146 stochastic programming model for the reliability analysis of soil slopes that simultaneously
147 considers the shear parameters of soil and the randomness of groundwater level.

148 In this study, a non-common-node triangular element is used to discrete the soil slope (as shown in
149 Figure 2 (a)), which were proposed by Sloan (Sloan and Kleeman. 1995). Each node has velocity
150 along the direction x and y , as well as pore water pressure.

151 The velocity vector of finite element \mathbf{u}^e can be expressed as:

$$152 \quad \mathbf{u}^e = [u_{x1}^e \quad u_{y1}^e \quad u_{x2}^e \quad u_{y2}^e \quad u_{x3}^e \quad u_{y3}^e]^T \quad (4)$$

153 where $e = (1, \dots, n_e)$, n_e is the quantity of finite elements in the soil slope, and u_{xi}^e, u_{yi}^e are the
154 velocity of nodes i ($i = 1, \dots, 3$) in the finite element e along the x or y direction, respectively.

155 To construct the kinematically admissible velocity fields of the soil slope, there should be a velocity
156 discontinuity between adjacent finite elements, as shown in Figure 2 (b). The velocity vector of the

157 velocity discontinuity can be expressed as:

$$158 \quad \mathbf{u}^d = [u_{x1}^d \quad u_{y1}^d \quad u_{x2}^d \quad u_{y2}^d \quad u_{x3}^d \quad u_{y3}^d \quad u_{x4}^d \quad u_{y4}^d]^T \quad (5)$$

159 where $d = (1, \dots, n_d)$, n_d is the quantity of the velocity discontinuities in the soil slope, u_{xi}^d, u_{yi}^d are
 160 the velocity of the i th ($i = (1, \dots, 4)$) node on the velocity discontinuity d along the x or y direction,
 161 respectively. Nodes ① and ③ belong to the finite element a , and nodes ② and ④ belong to the
 162 finite element b .

163 The pore water pressure vector \mathbf{p}_e^r of triangular element in the soil slope is defined as:

$$164 \quad \mathbf{p}_e^r = [p_{e1}^r \quad p_{e2}^r \quad p_{e3}^r]^T \quad (6)$$

165 where $e = (1, \dots, n_e)$; $p_{e1}^r, p_{e2}^r, p_{e3}^r$ are the random variables of the pore water pressure at nodes ①,
 166 ②, and ③ in the finite element e , respectively, which are directly related to H_w^r of the soil slope.

167 When considering the randomness of shear parameters and groundwater level, the velocity field is
 168 related to random parameters c^r, φ^r and \mathbf{p}_e^r . Therefore, a stochastic programming model of the
 169 upper bound method for soil slope reliability needs to be established based on plastic flow
 170 constraints of elements and discontinuities, velocity boundary conditions and objective function of
 171 the upper bound analysis. Based on plastic flow constraints of elements and discontinuities, velocity
 172 boundary conditions and objective function, a stochastic programming model of the upper bound
 173 method for soil slope reliability with a random seepage field is:

$$174 \quad \left\{ \begin{array}{l} Z = \lambda_m^r - 1.0 \\ \text{Minimise: } \lambda_\gamma^r = \mathbf{W}_{In1} + \mathbf{W}_{In2} - \mathbf{W}_{Ex2} - \mathbf{W}_{Ex3}^p - \mathbf{W}_{Ex4}^p \\ \text{Subject to: } \mathbf{A}_1^e \mathbf{u}^e - \mathbf{A}_2^e \boldsymbol{\lambda}^e = 0; \boldsymbol{\lambda}^e \geq 0; e = (1, \dots, n_e) \\ \mathbf{A}_1^d \mathbf{u}^d - \mathbf{A}_2^d \boldsymbol{\lambda}^d = 0; \boldsymbol{\lambda}^d \geq 0; d = (1, \dots, n_d) \\ \mathbf{A}^b \mathbf{u}^b = 0; b = (1, \dots, n_b) \\ \mathbf{W}_{Ex1}^e = 1.0 \end{array} \right. \quad (7)$$

175 where \mathbf{W}_{In1} is the internal power of elements; \mathbf{W}_{In2} is the internal power of the velocity
 176 discontinuities; \mathbf{W}_{Ex1} is the external work power exerted by the dead weight on the velocity of the
 177 element nodes; \mathbf{W}_{Ex2} is the external power exerted by concentrated force and distributed load at
 178 the velocity of the element nodes; \mathbf{W}_{Ex3}^p is the external work power of the pore water pressure in
 179 the element continuous body; \mathbf{W}_{Ex4}^p is the external work power exerted by pore water pressure on
 180 the velocity discontinuities; \mathbf{A}_1^e and \mathbf{A}_2^e are the matrixes of plastic flow constraint conditions of
 181 element; \mathbf{A}_1^d and \mathbf{A}_2^d are the matrixes of plastic flow constraint conditions of velocity
 182 discontinuity; \mathbf{A}^b is the coordinate transformation matrix of the boundary element and \mathbf{u}^b is the
 183 velocity vector of the boundary element. The meaning of the symbols can be referred to literature
 184 (Zhang et al. 2018; Sloan and Kleeman. 1995).

185 $\mathbf{A}_2^e, \mathbf{A}_2^d, \mathbf{W}_{m1}, \mathbf{W}_{m2}, \mathbf{W}_{Ex3}^p$, and \mathbf{W}_{Ex4}^p are all random matrices related to the random variables (e.g.,
 186 soil cohesion c^r , internal friction angle φ^r , and groundwater level H_w^r). Therefore, Equation (7)
 187 is a stochastic programming problem with the safety factor as the objective function, the soil shear
 188 parameter c^r, φ^r , and the ground water level H_w^r as the random variables, and velocity $\mathbf{u}_e, \mathbf{u}^d$
 189 and plasticity multiplier λ_e, λ^d as the decision variables.

190 **Solution of the stochastic programming model**

191 Equation (7) is a large-scale stochastic programming model. To obtain its solution, we must solve
 192 for the upper bound solution of the safety factor according to the characteristics of the soil shear
 193 parameters and the random variables of groundwater level. For large-scale stochastic programming
 194 problems, there has been no direct solution to date. Therefore, an iterative method based on the
 195 Monte Carlo method is proposed to obtain the solution. The numerical iterative method of the
 196 reliability upper bound method for stochastic programming model with a random seepage field is as
 197 follows:

198 (1) Generating the random number of the ground water level of soil slope. Assuming that the
 199 variation of the groundwater level H_w^r conforms to the truncated normal distribution (Shadabfar et
 200 al. 2020). Using the Monte Carlo method to determine H_w^r , the random number of the groundwater
 201 level of the soil slope is then generated as following:

$$202 \begin{cases} H_w^r(t_w) = rand(Normal, \mu_w, \sigma_w, 1, n_w) \\ H_{lb} \leq H_w^r(t_w) \leq H_{ub} \end{cases} \quad (8)$$

203 where $t_w = (1, \dots, n_w)$, n_w is the quantity of the Monte Carlo random numbers of the groundwater
 204 level of the soil slope, $H_w^r(t_w)$ is the t_w th random number of the groundwater level of the soil
 205 slope, μ_w is the mean groundwater level of the soil slope, σ_w is the standard deviation of the
 206 groundwater level of the soil slope, $rand$ is the normally distributed random number generation
 207 function, $Normal$ means that the random number conforms to the normal distribution, H_{lb} is the
 208 lower bound of the groundwater level of the soil slope, which takes the lowest water level, and H_{ub}
 209 is the upper bound of the groundwater level of the soil slope, which takes the highest water level.

210 (2) Generating the random numbers of the soil cohesion and the internal friction angle of the soil
 211 slope. It is assumed that the cohesion and friction angle of the soil material conform to a logarithmic
 212 normal distribution, and the random numbers of the material cohesion and the friction angle are
 213 generated as the following:

$$214 \begin{cases} c^r(t_m) = rand(lognormal, \mu_c, \sigma_c, 1, n_m) \\ \varphi^r(t_m) = rand(lognormal, \mu_\varphi, \sigma_\varphi, 1, n_m) \end{cases} \quad (9)$$

215 where $t_m = (1, \dots, n_m)$, n_m is the quantity of material for the soil cohesion and the friction angle of
 216 the Monte Carlo random number, $c^r(t_m)$ is the t_m th random number on the materials of the soil
 217 cohesion, $\varphi^r(t_m)$ is the t_m th random number of the friction angle of the soil material, μ_c is the
 218 mean value of the material cohesion of the soil, μ_φ is the mean value of the friction angle of the
 219 soil material, σ_c is the standard deviation of the soil cohesion, σ_φ is the standard deviation of the
 220 friction angle of the soil materials, and *lognormal* means the random number that has a
 221 logarithmic normal distribution.

222 Using the Monte Carlo Method to determine the random variables, the volume weight overload
 223 factor of soil slope is defined as:

$$224 \quad \lambda_\gamma(t_w, t_m) = \frac{\gamma_c(c^r(t_m), \varphi^r(t_m), H_w^r(t_w))}{\gamma_a} \quad (10)$$

225 where $t_w = (1, \dots, n_w)$, $t_m = (1, \dots, n_m)$, $\lambda_\gamma(t_w, t_m)$ is the volume weight overload factor
 226 corresponding to the random number of the t_m th random shear parameter for the t_w th groundwater
 227 level, and $\gamma_c(c^r(t_m), \varphi^r(t_m), H_w^r(t_w))$ is the ultimate volume weight of the soil slope in the limit
 228 state when it reaches the instability due to the t_w th groundwater level, which is related to the t_m th
 229 random shear parameters.

230 Using the Monte Carlo Method to determine the random variables while considering both the shear
 231 parameters and the randomness of the ground water level, the safety factor of the soil slope due to
 232 the groundwater level is then defined as:

$$233 \quad \lambda_m(t_w, t_m) = \frac{c^r(t_m)}{c^{vr}(t_m)} = \frac{\varphi^r(t_m)}{\varphi^{vr}(t_m)} \quad (11)$$

234 where $t_w = (1, \dots, n_w)$, $t_m = (1, \dots, n_m)$, $\lambda_m(t_w, t_m)$ is the safety factor of the random number
 235 corresponding to the t_m th random shear parameter under the action of the t_w th groundwater level,
 236 $c^{vr}(t_m)$ is the t_m th random number of the soil cohesion after strength reduction, and $\varphi^{vr}(t_m)$ is the
 237 t_m th random number of the internal friction angle of soil after strength reduction.

238 (3) Taking $H_w^r(t_w)$ as the water head boundary condition for the calculation of the stable seepage
 239 field, the n_w stable seepage fields of the soil slope are calculated from $t_w = 1$ to $t_w = n_w$ (Lu and
 240 Griffiths. 2004), and the random pore water pressure at each finite element node in the soil slope is
 241 then obtained: $p_{e1}^r(t_w), p_{e2}^r(t_w), p_{e3}^r(t_w)$, where $t_w = (1, \dots, n_w)$, $e = (1, \dots, n_e)$.

242 (4) Repeating $p_{e1}^r(t_w), p_{e2}^r(t_w), p_{e3}^r(t_w)$ from $t_w = 1$ to $t_w = n_w$, the random pore water pressure at
 243 all nodes in the n_w seepage fields is successively substituted into the stochastic programming
 244 model of the soil slope reliability (Equation (7)). $c^r(t_m)$ and $\varphi^r(t_m)$ are nested from $t_m = 1$ to

245 $t_m = n_m$ in each iterative loop from $t_w = 1$ to $t_w = n_w$. Substituting the soil material cohesion and
246 the random number of the friction angle in group n_m into Equation (7), Equation (7) then becomes
247 a linear programming problem in which all constraint matrices are fixed values. The upper bound
248 method linear programming model of the soil slope reliability is solved by using the dual simplex
249 optimization algorithm in IBM's CPLEX software (IBM.2016). The random number
250 $[\lambda_\gamma(t_w, t_m), t_w = 1, \dots, n_w, t_m = 1, \dots, n_m]$ and the corresponding velocity fields of $n_w \times n_m$ volume
251 weight overload factors are obtained through iterative calculation.

252 (5) In each iteration from $t_m = 1$ to $t_m = n_m$, "dichotomy" is used to iteratively solve $n_w \times n_m$ safety
253 factors $[\lambda_m(t_w, t_m), t_w = 1, \dots, n_w, t_m = 1, \dots, n_m]$ and the corresponding velocity field of the soil slope.
254 For each safety factor, the "dichotomy" iteration is used to calculate the volume weight overload
255 coefficient about 10 to 12 times. The specific iteration process is shown in Figure 3.

256 (6) The result of the safety factor is substituted into the limit state equation to calculate the reliability
257 index of the slope. Based on the calculation results, the safety factor histogram, the probability
258 density curve and the cumulative probability density curve of the soil slope, as well as the mean
259 value and standard deviation of the safety factor, are plotted. The relation diagram of the change of
260 the water level under the failure probability of the slope and the velocity field of the slope are
261 plotted.

262 In this study, *Python* is used to program the upper bound method for the slope reliability with the
263 random seepage field. The calculation program consists of three parts: the pre-processing module,
264 the computational module, and the post-processing module. Due to the large scale of the
265 computational samples, in order to improve the computational efficiency, the Parallel Computing
266 Toolbox in *Python* (John V Guttag. 2013) is used to develop a Parallel optimization solution
267 program. The optimization solution is solved by calling the dual simplex method in *Cplex* 12.71.
268 The program is able to run stably on a workstation (Processor: AMD ThreadRipper 3970X with 32
269 Cores, Physical Memory: 128GB) with high efficiency.

270 **Element failure probability of soil slope**

271 ***Integrated failure probability (IFP)***

272 Traditional slope failure analysis mainly applies the integrated failure probability method, which
273 solves the integrated failure probability of the slope according to the safety factor of the slope
274 (Griffiths and Fenton.2004; Phoon and Kulhawy.1999). Many commercial software products, such
275 as GEO-Slope, SLIDE, use this method to compute the slope failure probability. The calculation
276 principle states that when the safety factor of the slope is greater than or equal to 1.0, the slope is
277 stable (overall safety), and when the safety factor of the slope is smaller than 1.0, the slope is
278 unstable (overall failure). The failure function of the slope used in the integrated failure probability

279 method is:

$$280 \quad I_z(t_w, t_m) = \begin{cases} 0, & \text{if } \lambda_m(t_w, t_m) \geq 1.0 \\ 1, & \text{if } \lambda_m(t_w, t_m) < 1.0 \end{cases} \quad (12)$$

281 where $t_w = (1, \dots, n_w)$, $t_m = (1, \dots, n_m)$, and $I_z(t_w, t_m)$ is the failure function of the soil slope
282 corresponding to the random number of the t_m th random shear parameter for the t_w th groundwater
283 level.

284 The integrated failure probability of the slope for groundwater level t_w is:

$$285 \quad P_f^z(t_w) = \frac{1}{n_m} \sum_{t_m=1}^{n_m} I_z(t_w, t_m) \times 100\% \quad (13)$$

286 where $t_w = (1, \dots, n_w)$ and $P_f^z(t_w)$ is the integrated failure probability of the slope for the t_w th
287 groundwater level.

288 The integrated failure probability P_F^z of the soil slope for all groundwater levels is:

$$289 \quad P_F^z = \frac{1}{n_w \times n_m} \sum_{t_w=1}^{n_w} \sum_{t_m=1}^{n_m} I_z(t_w, t_m) \times 100\% = \frac{1}{n_w} \sum_{t_w=1}^{n_w} P_f^z(t_w) \quad (14)$$

290 ***Element failure probability (EFP)***

291 The integrated failure probability Equation (13) is widely used in the calculation of the slope failure
292 probability. However, there are some shortcomings in this method: (1) Equation (13) only considers
293 the size of the safety factor and does not consider the failure range of the soil corresponding to each
294 safety factor. Therefore, the failure probability does not correspond to the failure modes; (2)
295 Equation (13) implicitly assumes that the slope has only a single failure mode, which is inconsistent
296 with the existence of the multiple failure modes in the slope (Huang et al. 2013; Zhang et al. 2018).
297 To overcome these shortcomings, the authors proposed a new method for the failure analysis of the
298 rock slope – the element failure probability method (Li et al. 2019). According to the theory of the
299 upper bound method, when the mass element of the rock slope has plastic flow, it will have a relative
300 velocity based on the fixed element on the boundary. Therefore, in the velocity field obtained by the
301 upper bound method, when the element velocity is greater than 0, the element has plastic flow
302 (element failure). When the element velocity is equal to 0, the element does not have plastic flow
303 (element safety). In this method, the probability of the failure of the rock slope is calculated by using
304 the safety factor, and the location information of the failure element is used to calculate the spatial
305 distribution of the failure area of the rock slope. The failure probability of the rock slope with
306 multiple failure modes can be accurately calculated. Based on (Li et al. 2019), this study takes the
307 soil slope as the research object, applies the finite element to discrete the soil slope and considers the

308 effect of the random groundwater level on the slope stability. Both the shear parameters and the
 309 random groundwater level parameter samples are considered in defining the element failure
 310 probability of the soil slope. The failure function of the finite element e of the soil slope is defined
 311 as:

$$312 \quad I_e(t_w, t_m) = \begin{cases} 0 & \text{if } \lambda_m(t_w, t_m) \geq 1.0 \\ 0 & \text{if } \lambda_m(t_w, t_m) < 1.0 \text{ and } u_c^e(t_w, t_m) = 0 \\ 1 & \text{if } \lambda_m(t_w, t_m) < 1.0 \text{ and } u_c^e(t_w, t_m) > 0 \end{cases} \quad (15)$$

313 where $t_w = (1, \dots, n_w)$, $t_m = (1, \dots, n_m)$, and $e = (1, \dots, n_e)$; $I_e(t_w, t_m)$ is the failure function of the
 314 finite element e corresponding to the random number of the t_m th shear parameter under the action
 315 of the t_w th groundwater level, $\lambda_m(t_w, t_m)$ is the random number of the safety factor related to the
 316 random number $c^r(t_m), \varphi^r(t_m)$ of the t_m th shear parameter for the t_w th groundwater level,
 317 $u_c^e(t_w, t_m)$ is the resultant velocity at the centre of the finite element e in the velocity field calculated
 318 by using the random number $c^r(t_m), \varphi^r(t_m)$ of the t_m th shear parameter under the action of the t_w th
 319 groundwater level.

320 The resultant velocity $u_c^e(t_w, t_m)$ at the centroid of the finite element e is calculated as:

$$321 \quad u_c^e(t_w, t_m) = \sqrt{\left(\frac{1}{3} \sum_{i=1}^3 u_{xi}^e(t_w, t_m)\right)^2 + \left(\frac{1}{3} \sum_{i=1}^3 u_{yi}^e(t_w, t_m)\right)^2} \quad (16)$$

322 where $t_w = (1, \dots, n_w)$, $t_m = (1, \dots, n_m)$, $e = (1, \dots, n_e)$, $u_{xi}^e(t_w, t_m)$, and $u_{yi}^e(t_w, t_m)$ are the velocities
 323 of node i ($i = (1, 2, 3)$) in the finite element e along the x and y direction calculated by using the
 324 random number $c^r(t_m), \varphi^r(t_m)$ of the t_m th shear parameter for the t_w th groundwater level.

325 The specific meaning of Equation (15) is the following:

326 (1) When the safety factor of the slope is greater than or equal to 1, i.e. $\lambda_m(t_w, t_m) \geq 1.0$, the slope
 327 remains stable and all elements in the slope do not fail. Therefore, the failure function of the finite
 328 element e is $I_e(t_w, t_m) = 0$.

329 (2) When the safety factor of the slope is smaller than 1, i.e. $\lambda_m(t_w, t_m) < 1.0$, the slope is unstable. At
 330 the same time, if the centroid velocity of a finite element e in the slope is equal to 0, i.e.,
 331 $u_c^e(t_w, t_m) = 0$, no plastic flow will occur in this element, and no failure will occur in this element. At
 332 this time, the failure function of the finite element e is $I_e(t_w, t_m) = 0$.

333 (3) When the safety factor of the slope is smaller than 1.0, i.e., $\lambda_m(t_w, t_m) < 1.0$, the slope is unstable.
 334 At the same time, if the element velocity of finite element e in the slope is larger than 0, i.e.
 335 $u_c^e(t_w, t_m) > 0$, plastic flow occurs in this element, and the element fails. At this point, $I_e(t_w, t_m) =$
 336 1.0.

337 The failure probability of the soil slope for ground water level t_w is calculated as:

338
$$P_f^e(t_w) = \frac{1}{n_m} \sum_{t_m=1}^{n_m} I_e(t_w, t_m) \times 100\% \quad (17)$$

339 where $t_w = (1, \dots, n_w)$, $e = (1, \dots, n_e)$, and $P_f^e(t_w)$ is the failure probability of the finite element e in
 340 the soil slope for the t_w th groundwater level.

341 The element failure probability of the slope for all possible groundwater levels is calculated as:

342
$$P_F^e = \frac{1}{n_w \times n_m} \sum_{t_w=1}^{n_w} \sum_{t_m=1}^{n_m} I_e(t_w, t_m) \times 100\% = \frac{1}{n_w} \sum_{t_w=1}^{n_w} P_f^e(t_w) \quad (18)$$

343 where $e = (1, \dots, n_e)$ and P_F^e is the failure probability of the finite element e in the slope for all
 344 possible groundwater levels.

345 **Validation and application**

346 To verify the rationale and correctness of the proposed reliability upper bound analysis method of
 347 the soil slope for random seepage fields, a classical calculation example of the heterogeneous soil
 348 slope is selected. The stability of the slope is calculated and analysed with the program written by
 349 the authors.

350 *Basic information regarding heterogeneous soil slopes*

351 The example selected in this study is a heterogeneous slope with two layers of soil (as shown in
 352 Figure 4) (Ji et al. 2017). The top width of the heterogeneous slope is 40.0 m, the total height is 28.0
 353 m, the slope height is 24.0 m, and the slope ratio of the slope surface is 0.75:1.0. The thickness of
 354 soil layer 1 is 18.0 m and is 10.0 m for the soil layer 2. The groundwater level on the right side of the
 355 slope is H_w^r , and the groundwater level at the left slope angle is flush with the surface. In this study,
 356 the volume weight and the permeability coefficient of the slope soil material are set as the
 357 determined values, and the cohesion, the internal friction angle, and the right groundwater level
 358 H_w^r of the two layers of the soil material are set as random variables. The finite element grid of the
 359 slope is shown in Figure 4. The slope is divided into 624 finite elements, 765 velocity
 360 discontinuities, and 1,404 finite element nodes. The purpose of this example is to: (1) calculate the
 361 mathematical distribution of the safety factor for the random groundwater level; (2) calculate the
 362 probability density curve of the safety factor and the cumulative probability density curve based on
 363 the random groundwater level; and (3) calculate the relationship between the integrated failure
 364 probability, the element failure probability, and the groundwater level.

365 *Random dispersion of shear parameters of slope soil*

366 The heterogeneous slope is composed of two soil layers. The statistical values of the physical and
 367 mechanical parameters of the two soil materials are shown in Table 1. The shear parameter of the

368 lower layer is 1.5 times that of the upper layer. In this study, it is assumed that both the cohesion and
369 the internal friction angle of soil layer conform to a logarithmic normal distribution. Because the
370 sample is very large, this study does not consider the correlation of the soil shear parameters in the
371 two layers. The quantity of random numbers n_m for the soil cohesion and the internal friction is
372 4,000. Based on the shear parameters of the mean value and coefficient of variation, the random
373 number of the shear parameter is obtained by discretizing Equation (9). The random distribution of
374 the soil cohesion and the internal friction angle is shown in Figure 5 and Figure 6.

375 ***Random groundwater level and random seepage field of slope***

376 In this study, it is assumed that the groundwater level conforms to the truncated normal distribution.
377 The mean μ_w of the groundwater level H_w^r is set as 16.0 m, the coefficient of variation δ_w is set
378 as 0.25, and the standard deviation σ_w is set as 4.0. The lower bound H_{lb} of the groundwater
379 level H_w^r is set as 4.01 m, and the upper bound H_{ub} is set as 27.99 m. The number of random
380 numbers for the groundwater level n_w is set as 50. The groundwater level at the edge slope angle is
381 set as 10.0 m. According to Equation (8), 50 random numbers for the groundwater level of H_w^r can
382 be obtained discretely (as shown in Table 2). The histograms of 50 random groundwater level
383 numbers are shown in Figure 6. Among the 50 random numbers, the frequency of the random
384 numbers near the mean value is relatively high, with 21 random numbers appearing between 15.0 m
385 and 18.0 m. The frequency of both the high water level and the low water level is relatively low. The
386 groundwater level sample below 5.0 m appears twice, and the groundwater level sample above 27.0
387 m appears once.

388 According to the random number $H_w^r(t_w)$ of 50 groundwater levels, 50 stable seepage fields of the
389 heterogeneous soil slopes are calculated. Pore-water pressure at all nodes in each seepage field is
390 obtained. Figure 7 depicts the contour map of the pore water pressure of the slope for $H_w^r(10) =$
391 10.9536 m, $H_w^r(30) = 16.7785$ m, $H_w^r(40) = 19.3883$ m, and $H_w^r(50) = 27.1907$ m. When the
392 local lower water level is low, the variation of the pore water pressure contour line is relatively
393 gradual; when the local lower water level is gradually increasing, the infiltration line is gradually
394 increasing, and the pore water pressure contour line also becomes steep.

395 Figure 8 shows the variation of the pore water pressure with the water level at three key points in the
396 slope (see Figure 4 for details of the location of the key points). The coordinates of these three key
397 points are P1 (20.00, 4.00), P2 (31.98, 4.00), and P3 (44.00, 4.00), respectively. It is seen that the
398 pore water pressure at three locations increases gradually with the increase of the groundwater level.

399 Figure 9 shows the histogram of 50 random pore water pressures at these three locations. It is seen
400 that the frequency distribution of the pore water pressure is high in the middle and low on both sides.

401 The mean pore water pressure at locations P1, P2, and P3 is -37.28, -59.88, and -77.45 kPa,

402 respectively, and the standard deviations of the pore water pressure are 18.05, 29.02, and 36.93,
403 respectively.

404 *Analysis of the distribution of slope safety factor*

405 According to the stochastic mathematical model Equation (7) of the upper bound method and the
406 calculation process (Figure 3), the reliability of the soil slope is calculated by taking the soil shear
407 parameters and the randomness of the ground water level into account. For each group of
408 groundwater levels, 4,000 groups of the shear parameter samples are investigated. In total,
409 $50 \times 4,000 = 200,000$ samples are calculated. The upper bound solutions of 200,000 safety factors
410 and the corresponding velocity fields are obtained. Based on the parallel computational program
411 developed in this study, the calculation on a small workstation (Processor: AMD ThreadRipper
412 3970X with 32 Cores, Physical Memory: 128GB) takes approximately 74 hours for 200,000
413 samples with an average time of 1.33 s for each sample.

414 To verify the proposed model, we compare the calculated results from the upper bound method with
415 the results from the rigid body limit equilibrium method. Two different groundwater levels are
416 considered for comparative analysis, namely, $H_w^r(1) = 4.1234$ m (the first sample) and $H_w^r(47) =$
417 24.8945 m (the 47th sample). To execute the rigid body limit equilibrium method, the Probabilistic
418 Analysis module in GEO-Slope, a widely used commercial software product, is used to calculate the
419 reliability of the slope stability, while the Bishop method is used to calculate the slope stability. The
420 safety factor and the integrated failure probability calculated by the two methods are shown in Table
421 3. The failure mode of the slope is shown in Figure 10. The comparison of the cumulative
422 probability density curve of the slope safety factor is shown in Figure 11. The analysis and
423 calculation results show that:

424 (1) The upper bound solutions of the mean value and the standard deviation of the slope safety
425 factor are smaller than those calculated by the Bishop method. The difference of the slope safety
426 calculated using two methods decreases with the increase of the groundwater level. At a low
427 groundwater level ($H_w^r(1) = 4.1234$ m), the mean difference in the safety factors is 1.5%, and the
428 difference in the standard deviations is 35.1%. At a high groundwater level ($H_w^r(47) = 24.8945$ m),
429 the mean difference between the safety factors is 0.53%, while the difference in standard deviations
430 is 6.4%.

431 (2) In terms of slope failure mode, only a shallow slope landslide occurs for the low water level
432 ($H_w^r(1) = 4.1234$ m) when the Bishop method is used (as shown in Fig. 10a); for the high water
433 level ($H_w^r(47) = 24.8945$ m), only a deep slope landslide occurs, and the upper and lower soil
434 masses are unstable simultaneously (as shown in Fig. 10b). However, when the upper bound method
435 is used to calculate the slope, a shallow landslide and a deep landslide may occur regardless of the

436 groundwater level. The velocity fields of a shallow landslide and a deep landslide are shown in
437 Figure 10.

438 (3) The integrated failure probability $P_f^z(t_w)$ of the slope, as shown in Table 3, demonstrates that
439 there is a large difference between the calculated integrated failure probabilities produced by the
440 upper bound method and the Bishop method. At a low groundwater level (e.g. $H_w^r(1) = 4.1234$ m),
441 the upper bound solution of the integrated failure probability $P_f^z(1)$ is 0.4%, which is less than that
442 in the high groundwater level (e.g. 0.80% at $H_w^r(47) = 24.8945$ m). This is consistent with the
443 actual law. However, when the Bishop method is used, the integrated failure probability is 1.88% at
444 the low groundwater level ($H_w^r(1) = 4.1234$ m) and is 1.01% at the high groundwater level
445 ($H_w^r(47) = 24.8945$ m), which is inconsistent with the actual law. The main reason for this
446 abnormal phenomenon is that the critical slip surface in the Bishop method is calculated according
447 to the mean value of shear parameters. When the safety factor is calculated using other shear
448 parameter samples, the possibility of deep sliding is ignored at the low groundwater levels, and the
449 possibility of shallow sliding is ignored at the high groundwater levels (as shown in Fig. 10).

450 (4) Figure 11 shows that the cumulative probability density curve of the Bishop solution is higher
451 than that of the upper bound solution. The difference of the solutions by two methods increases with
452 the decrease of the groundwater level. It is mainly due to the fact that the Bishop method does not
453 fully consider all failure modes of the slope. Actually, the slope is dominated by shallow landslide at
454 the low groundwater level; on the contrary, the slope is dominated by deep landslide at the high
455 groundwater level. However, The Bishop method only considers shallow instability at the low
456 groundwater level and deep instability at the high groundwater level.

457 According to Fig. 3, the upper bound method is used to calculate the safety factor of the slope
458 stability for 50 groundwater levels. The distribution histogram of the upper bound solution of the
459 safety factor at $t_w = 10, 30, 40,$ and 50 is shown in Figure 12. The 50 probability density curves and
460 cumulative probability density curves of the slope safety factor are shown in Figure 13 and Figure
461 14. The mean value and standard deviation of the slope safety factor are shown in Figure 15 and
462 Figure 16. Analysis of these figures shows the following: (1) The safety factor of the slope generally
463 fits with the normal distribution. With the rise of the groundwater level, the mean value of the safety
464 factor gradually decreases, and the probability density curve and the cumulative probability density
465 curve gradually shift to the left. This finding indicates that the higher the groundwater level is, the
466 lower the safety of the slope is. (2) As the groundwater level rises, the standard deviation of the
467 safety factor gradually decreases, the distribution range of the probability density curve gradually
468 becomes narrow, and the cumulative probability density curve gradually steepens. (3) According to
469 the polynomial fitting of the data of the mean value and standard deviation of the safety factor, the

470 relationship between the standard deviation of the safety factor and the groundwater level can be
471 obtained as:

$$472 \quad Std = 0.000003H_w^3 - 0.000148H_w^2 + 0.001101H_w + 0.265096 \quad (19)$$

473 The mean value and standard deviation of the safety factor are negatively correlated with the
474 groundwater level.

475 (4) Both the histograms of the mean value and standard deviation of the safety factor are low on both
476 sides and high in the middle, which is similar to the distribution of the groundwater head. The mean
477 maximum frequency of the safety factor is between 1.56 and 1.57, and the maximum frequency was
478 14 times. The highest frequency of the standard deviation of the safety factor occurs between 0.255
479 and 0.258, and the highest frequency is 11 times.

480 (5) The 200,000 safety factors calculated by the upper bound method are statistically analysed to
481 obtain the distribution characteristics of the random slope safety factors, which take into account
482 both the groundwater level and the shear parameters, as shown in Figure 17. The probability density
483 curve and the cumulative probability density curve of the 200,000 safety factors are given in Figure
484 18. The mean value of the upper bound solution of 200,000 safety factors is 1.569 and the standard
485 deviation is 0.260.

486 *Failure probability analysis of slope*

487 In this study, two methods are used to analyse the failure of the slope, which are the traditional
488 integrated failure probability method and the element failure probability method developed in this
489 study.

490 According to Equations (13), the integrated failure probability of homogeneous soil slopes under
491 the action of 50 random groundwater levels is calculated, as shown in Table 4. The variation of the
492 integrated failure probability of the slope for groundwater level t_w is shown in Figure 19. When the
493 local underground water level gradually increases, the integrated failure probability of the slope
494 gradually increases from 0.40% to 1.425%, and the safety of the slope gradually decreases.
495 According to the data of discrete point $P_f^z(t_w)$ of integrated failure probability, the relationship
496 between the integrated failure probability and the groundwater level can be obtained by best fitting:

$$497 \quad P_f^z = -0.00044H_w^5 + 0.00689H_w^4 - 0.06596H_w^3 + 0.37341H_w^2 - 1.13746H_w + 1.82329 \quad (20)$$

498 The above equation shows that the relationship between the integrated failure probability of the
499 slope and the groundwater level is a 5-power polynomial. The integrated failure probability of the
500 slope changes only slightly when the local water level is within the range of 4.0 m to 20.0 m. When
501 the local lower water level is greater than 20.0 m, the integrated failure probability of the slope

502 increases rapidly, indicating that the higher the groundwater level is, the greater the integrated
503 failure probability of the slope is.

504 According to Equation (14), the integrated failure probability of the slope under the action of all
505 possible groundwater levels is calculated to be $P_F^z = 0.487\%$. According to the calculation of the
506 integrated failure probability, the relationship between P_F^z and $P_f^z(t_w)$ is $P_F^z = \sum_{t_w=1}^{n_w} P_f^z(t_w) / n_w$, that
507 is, P_F^z is the average value of $(P_f^z(t_w), t_w = (1, \dots, n_w))$.

508 Fifty random seepage fields of inhomogeneous soil slope for element failure probability are
509 calculated based on Equation (17). Figure 20 shows the slope element failure probability contour for
510 $t_w = 5, 30, 40, 42, 45$ and 50 , while Figure 21 shows the failure mode of the slope velocity field.
511 The relationship between element failure probability and groundwater level of a characteristic
512 element is shown in Figure 22. Figures 20 - 22 show:

513 (1) When the local lower groundwater level is less than 20.0 m ($t_w \leq 40$) (as shown in Figure 20 (a,
514 b, c)), the failure element is mainly located slope in the upper soil mass. At this time, only a shallow
515 landslide occurs in the slope, and the failure area of the slope is consistent with that calculated by the
516 Bishop method (see Figure 11 (a)). When groundwater level is between 4.0 m and 20.0 m, the slope
517 failure is mainly in the range of a height of 10.0 m to 28.0 m in the upper layer soil. The maximum
518 element failure probability in the upper soil changes between 0.400 and 0.475%. The main reason is
519 that the saturation line of pore water pressure on the slope of the upper soil has an insignificant
520 effect and the upper soil pore water pressure is zero. The stability of the slope is not sensitive to the
521 change of the groundwater level.

522 (2) When the local lower groundwater level is greater than 20.0 m and gradually increases, the
523 failure probability of the element gradually increases, and the failure element of the slope gradually
524 moves towards the lower soil. The higher the groundwater level is, the more elements of deep
525 failure occur in the lower soil, as shown in Figure 20 (d) - (f). It can be seen from the figure that the
526 failure probability of the element of shallow soil is greater than that of the element of deep soil,
527 which indicates that the slope has both shallow and deep landslides when the groundwater level
528 rises. The probability of a shallow landslide is greater than that of a deep landslide.

529 (3) When the local lower groundwater level is greater than 20.0 m ($t_w > 40$), the distribution area of
530 failures of the slope gradually expands, which indicates that there are multiple failure modes in the
531 slope as the groundwater level increases. According to the statistical analysis of all the velocity
532 fields, there are four typical velocity fields when the slope fails, as shown in Figure 21. Among these
533 velocity fields, failure mode 1 and failure mode 2 belong to shallow failures, while failure mode 3
534 and failure mode 4 belong to deep failures. Theoretically, if there is only one failure mode of the
535 slope, the failure probability of each element in the sliding body area of the slope should be equal (as

536 shown in Figure 21 (a)). In contrast, if there are multiple failure modes in the slope, each failure
537 mode occurs at different times, and the failure area of each failure mode is different in size, then the
538 failure probability of each part of the slope is different. This property means that the failure
539 probability of elements in different positions of the soil is different (as shown in Figure 21 (e ~ f)).
540 When the groundwater level $H_w^r(45) = 22.5527$ m (as shown in Figure 21 (e)), the failure
541 probability of the soil area of the shallow landslide is between 0.258% and 0.650%, while the failure
542 probability of the soil area of the deep landslide is between 0.071% and 0.258%. When the local
543 water level rises to $H_w^r(50) = 27.1907$ m (as shown in Figure 21 (f)), the failure probability of the
544 soil area of the shallow landslide is between 0.552% and 1.425%, while the failure probability of the
545 soil area of the deep landslide is between 0.149% and 0.552%. In the multiple failure modes, the
546 overlapping soil area has the highest failure probability, as shown in the red area.

547 (4) The relationship between the failure probability of the five characteristic elements in the slope
548 and the groundwater level is shown in Figure 22, and the location of the five elements is shown in
549 Figure 4. As seen from the figure: (i) Under the action of the same groundwater level, the failure
550 probability of each part of the slope is different. (ii) The failure probability of the same element in
551 the slope is also different for different groundwater levels. The failure probability of the element is
552 positively correlated with the groundwater level. With the increase in groundwater level, the failure
553 probability of all elements increases gradually. (iii) The failure probability of the upper soil is higher
554 than that of the lower soil. Element E1 is located at the top of slope, and element E3 is located at the
555 bottom of the upper soil. Failure occurs in both the shallow and the deep landslides. Element E2 is
556 located at the slope foot, while element E4 and element E5 are located at the upper and middle part
557 of the subsoil, respectively. These three elements, E2, E4, and E5, only fail when the slope has a
558 deep landslide. When the local lower groundwater level is greater than 20.0 m ($t_w > 40$), both the
559 shallow and the deep landslides will occur in the slope at the same time. The failure probability of
560 the E1 and E3 elements of the upper soil increases faster than that of the E2, E4 and E5 elements.
561 When $t_w > 43$, the failure probability of the 5 elements adheres to the following rules: $E1 > E3 >$
562 $E2$ and $E4 > E5$.

563 (5) According to the calculation results of the traditional Bishop method, only shallow landslides
564 occur when the groundwater level is low, and only deep landslides occur when the groundwater
565 level is high. These limitations are caused by the calculation principle. The Bishop method
566 calculates the critical slip surface of slope according to the average shear parameters. According to
567 this critical slip surface with a random numbers of shear parameters, the reliability is then calculated
568 using the Monte Carlo calculation. Therefore, for each set of shear parameters from the random
569 sample, the critical slip surface obtained by the Bishop method is not realistic. Therefore, the failure

570 mode calculated by the Bishop method is not complete. The limitations of the Bishop method lead
571 to the ignorance of some samples of the failure mode. Based on the upper bound method, the
572 proposed element failure probability method can completely determine all the slope failure modes.
573 According to Equation (18), the element failure probability of the slope for all possible groundwater
574 levels is calculated. The contour map of the element failure probability of the slope is shown in
575 Figure 23. The maximum element failure probability of the slope is 0.4865%. The shallow landslide
576 failure occurs in the soil area surrounded by the 0.43% isoline. The element failure probability of the
577 deep landslide is 0.008 to 0.43%. Shallow failure is more likely than deep failure.

578 Through the example analysis in this study, the differences between IFP and EFP can be summarised
579 as follows:

580 (1) The IFP only determines whether the slope fails according to whether the safety factor of the
581 slope stability is less than 1.0 and IFP only reflects the degree of the failure probability of slope.
582 While the EFP proposed in this paper investigates the failure possibility of each element in the slope,
583 it simultaneously considers the two attributes of the slope failure, namely: the slope failure
584 probability is calculated by the safety factors, and the difference in the spatial distribution of the
585 slope failure area is calculated by the location information of the element. The safety degree of each
586 part of slope is accurately described by the EFP.

587 (2) The IFP is specific to the overall stability of the slope, while the EFP calculates the failure of
588 specific elements in the slope. EFP firstly judges the slope instability by the safety factor being less
589 than 1.0, under the condition of slope instability, the element failure can be judged by whether the
590 element velocity is greater than 0. Each element in the slope is in a different position, which
591 produces a different failure probability for each element. If the same samples of safety factors is
592 used by the IFP and the EFP, element failure probability must be equal to the integral failure
593 probability.

594 (3) For slopes with only one failure mode, the two methods have the same results. However, for
595 slopes with multiple failure modes, the EFP method is more accurate and efficient than the IFP.

596 **Conclusion**

597 This study provides a new approach for the reliability analysis of the soil slope stability, which is
598 based on the upper bound method of the plastic limit analysis theory, as it considers the shear
599 parameters of soil and the randomness of the groundwater level. The distribution of the safety factor
600 and the element failure probability of the soil slope by considering the randomness of the shear
601 parameters and the groundwater level is obtained.

602 The traditional slope failure analysis (IFP) has a large error when it is used to analysis the failure
603 probability of slope with multiple failure modes. This paper studies the possibility of each element

604 in the soil slope failure by considering the double attribute of the slope failure, that is, the
605 application of the safety factor probability of the slope failure and the application of the location
606 information of the element statistical differences in the spatial distribution of the slope failure area.
607 The results calculated using the element failure probability (EFP) method proposed in this study and
608 the traditional integrated failure probability method are similar under the single failure mode of the
609 slope. However, in the calculation of the slope failure probability with multiple failure modes, the
610 element failure probability method shows its advantage. The element failure probability method of
611 soil slopes for each element has the comprehensive safety assessment of the slope has reference
612 significance. The slope is transformed from "*integrated failure probability analysis*" to "*element*
613 *failure probability analysis*", which provides a new method for slope failure analysis.

614 **Data Availability Statement**

615 All data generated or used during the study are available from the corresponding author by request.

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622 **Appendix I. Notation**

623 *The following symbols are used in this paper:*

\mathbf{A}^b	=	coordinate transformation matrix of the finite element b on the boundary
\mathbf{A}_1^e	=	matrix of plastic flow constraint conditions of the finite element e
\mathbf{A}_2^e	=	matrix of plastic flow constraint conditions of the finite element e
\mathbf{A}_1^d	=	matrix of plastic flow constraint conditions of the velocity discontinuity d
\mathbf{A}_2^d	=	matrix of plastic flow constraint conditions of the velocity discontinuity d
c^r	=	random variables of the cohesion of the soil materials
c^{vr}	=	random quantity of cohesion after the intensity reduction
$c^r(t_m)$	=	the t_m th random number on the materials of the soil cohesion
$c^{vr}(t_m)$	=	the t_m th random number of the soil cohesion after strength reduction
H_w^r	=	random variable of the groundwater level of the soil slope
$H_w^r(t_w)$	=	the t_w th random number of the groundwater level of the soil slope
H_{lb}	=	the lower bound of the groundwater level of the soil slope
H_{ub}	=	the upper bound of the groundwater level of the soil slope
$I_z(t_w, t_m)$	=	failure function of the soil slope corresponding to the random number of the t_m the random shear parameter under the action of the t_w th groundwater level
$I_e(t_w, t_m)$	=	the failure function of the finite element e corresponding to the random number of the shear t_m th parameter under the action of the t_w th underground level
n_b	=	the quantity of the finite elements on the boundary of the soil slope
n_d	=	the quantity of the velocity discontinuities in the soil slope
n_e	=	the quantity of finite elements in the soil slope
n_m	=	the quantity of material for the soil cohesion and the friction angle of the Monte Carlo random number
n_w	=	the quantity of the Monte Carlo random numbers of the groundwater level of the soil slope
\mathbf{p}_e^r	=	pore water pressure vector of finite element e
$p_{ei}^r(t_w)$	=	the pore water pressure at nodes i ($i=1,2,3$) in finite element e under the action of t_w th groundwater level

p_{ei}^r	=	random variable of the pore water pressure at nodes i in finite element e
P_F^z	=	the integrated failure probability of the slope under the action of all possible groundwater levels
P_F^e	=	the failure probability of the finite element e in the slope under the action of all possible groundwater levels
$P_f^e(t_w)$	=	the failure probability of the finite element e in the soil slope under the action of the t_w th groundwater level
$P_f^z(t_w)$	=	the integrated failure probability of the slope under the action of the t_w th groundwater level
\mathbf{T}^b	=	transformation matrix of the finite element b on the boundary
\mathbf{T}^d	=	transformation matrix of the velocity discontinuity d
\mathbf{u}^b	=	velocity vector of the boundary finite element b
\mathbf{u}^d	=	velocity vector of the velocity discontinuity d
\mathbf{u}^e	=	velocity vector of finite element e
$u_c^e(t_w, t_m)$	=	resultant velocity at the centroid of the finite element e corresponding to the random number of the shear t_m th parameter under the action of the t_w th underground water level
u_{xi}^d	=	the velocity of the i th ($i=(1, \dots, 4)$) node on the velocity discontinuity plane d along the direction x
u_{yi}^d	=	the velocity of the i th ($i=(1, \dots, 4)$) node on the velocity discontinuity plane d along the direction y
u_{xi}^e	=	velocity of nodes i ($i=1, \dots, 3$) in the finite element e along the direction x
$u_{xi}^e(t_w, t_m)$	=	the velocity of node i ($i=(1, 2, 3)$) in the finite element e along the x direction calculated by using the random number $c^r(t_m), \phi^r(t_m)$ of the t_m th shear parameter under the action of the t_w th groundwater level.
u_{yi}^e	=	velocity of nodes i ($i=1, \dots, 3$) in the finite element e along the direction y
$u_{yi}^e(t_w, t_m)$	=	the velocity of node i ($i=(1, 2, 3)$) in the finite element e along the y direction calculated by using the random number $c^r(t_m), \phi^r(t_m)$ of the t_m th shear parameter under the action of the t_w th groundwater level.
\mathbf{W}_{Ex1}	=	external work power done by the dead weight on the velocity of the finite element nodes
\mathbf{W}_{Ex2}	=	external power done by concentrated force and distributed load at the

		velocity of the finite element nodes
\mathbf{W}_{Ex3}^p	=	external work power of the pore water pressure in the finite element continuous body
\mathbf{W}_{Ex4}^p	=	external work power done by pore water pressure on the finite element velocity discontinuities
\mathbf{W}_{In1}	=	internal power of finite elements
\mathbf{W}_{In2}	=	internal power of the velocity discontinuities
Z	=	limit state function of the soil slope reliability
γ_a	=	the real volume weight of the soil material
$\gamma_c(c^r, \varphi^r, H^r)$	=	random variable of the ultimate value of volume weight that relates to c^r , φ^r and H^r when the soil reaches the limit state
$\gamma_c(c^r(t_m), \varphi^r(t_m), H_w^r(t_w))$	=	the ultimate volume weight of the soil slope in the limit state when it reaches the instability related to the t_m th random shear parameter under the action of t_w th groundwater level
γ_e	=	volume weight of finite element e .
θ_d	=	inclination angle of the velocity discontinuity d ,
θ_b	=	dip angle of the boundary
λ^d	=	vector of non-negative plastic multiplier of the velocity discontinuity d
λ^e	=	vector of nonnegative plastic multiplier of finite element e
λ_m^r	=	the random variable of the safety factor that relates to c^r , φ^r and H^r
$\lambda_m(t_w, t_m)$	=	the safety factor of the random number corresponding to the t_m th random shear parameter under the action of the t_w th ground water level
λ_γ^r	=	random variable of the overload factor of volume weight that relates to c^r , φ^r and H^r
$\lambda_\gamma(t_w, t_m)$	=	volume weight overload factor corresponding to the random number of the random shear parameter t_m under the action of the t_w th ground water level
μ_c	=	the mean value of the material cohesion of the soil
μ_w	=	the mean groundwater level of the soil slope
μ_φ	=	the mean value of the friction angle of the soil material
σ_c	=	the standard deviation of the soil cohesion
σ_w	=	the standard deviation of the groundwater level of the soil slope

σ_φ	=	the standard deviation of the friction angle of the soil materials
φ^r	=	random variables of the internal friction angle of the soil materials
φ_d^r	=	random quantity of the internal friction angle of the velocity discontinuity plane d
φ_e^r	=	random quantity of friction angle of the finite element e of soil slope.
$\varphi^r(t_m)$	=	the t_m th random number of the friction angle of the soil material
φ^{vr}	=	random quantity of the internal friction angle after the intensity reduction
$\varphi^{vr}(t_m)$	=	the t_m th random number of the internal friction angle of soil after strength reduction

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